

Math 3160 - Test 2 Review

1 Vectors

- Find a unit vector that when positioned at the origin forms a 30° angle with the x-axis.
- Find a vector of length three units that when positioned at the origin forms a 240° angle with the x-axis.
- Let $\mathbf{v} = (1, 3, 4)$ and $\mathbf{w} = (1, -1, 0)$ be vectors in $\mathbb{R}^3$. and let $P(1, 1, 1)$ and $Q(0, -4, 0)$ be two points in $\mathbb{R}^3$.
 - Find a vector that is parallel to $\mathbf{v}$ and unit.
 - Compute $\|2\mathbf{v} - \mathbf{w}\|$.
 - Compute the angle between $\mathbf{v}$ and $\mathbf{w}$.
 - Find the equation of a plane containing P and with normal vector $\mathbf{v}$.
- Find the parametric equations for the line (in $\mathbb{R}^3$) so that
 - the line contains the point $P(0, 1, 2)$ and $Q(1, 2, 3)$.
 - the line contains the point $P(-5, 1, 3)$ and is parallel to the vector $(1, 2, 3)$.
- Find equation (both the normal equation and the parametric equation) for the plane (in $\mathbb{R}^3$) so that
 - the plane contains the points $P(2, 2, 2)$, $Q(1, 2, 3)$ and $R(1, -1, 0)$.
 - the plane contains the origin and is perpendicular to the vector $(1, 2, 3)$.
 - the plane contains the point $(1, 2, 3)$ and contains the vectors $\mathbf{v} = (1, 0, -3)$ and $\mathbf{w} = (2, 1, 3)$.
- Define the planes P_1 and P_2 as follows:

$$P_1 : x - 2y + z = 12$$

$$P_2 : 3x - 3y + z = 4$$

- What are the two normal vectors for the above planes.

- (b) Find the angle between the two above planes.
 - (c) Find two points one on each of the above planes.
 - (d) Find set of all points that lay in both planes.
 - (e) The two planes intersect in a line, find the parametric equation of that line.
7. Define the planes P_1 and P_2 as follows:

$$P_1 : x - 2y + z = 12$$

$$P_2 : 3x - 6y + 3z = 4$$

Show the planes are parallel. Do they intersect? Find the solution set to their intersection.

8. Let $P(1, 0, 2, 0)$, $Q(0, 0, 2, -1)$, $R(0, 1, 1, 0)$ and $S(1, 1, 1, 0)$ be points in $\mathbb{R}^4$. Find the equation of the hyperplane (both the normal equation and the) that contains these four points.
9. For the hyperplane (in $\mathbb{R}^5$) given below: find its normal vector and find its parametric equation.

$$x_1 + -4x_3 + 2x_4 + x_5 = 3$$

2 Vector Spaces and Subspaces

10. Let $V = \mathbb{R}^3$ equipped with usual vector addition and scalar multiplication. Prove V is a vector space. That is, prove all 10 Axioms.
11. Let $V = \mathbb{R}^2$. And define the two operations

$$\oplus: (x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2 + 1, y_1 + y_2 + 1)$$

$$\odot: k \odot (x_1, y_1) = (kx_1, ky_1)$$

- (a) Compute $(0, 4) \oplus (-2, 3)$ and compute $2 \odot (1, 1)$.
- (b) Show $\mathbf{0} \neq (0, 0)$.
- (c) Show $\mathbf{0} = (-1, -1)$.
- (d) Prove Axiom 5. That is, for each $\mathbf{v}$ find $-\mathbf{v}$ so that

$$\mathbf{v} \oplus -\mathbf{v} = \mathbf{0}.$$

- (e) V does satisfy some of the vector space axioms, but not all of the axioms. Find two axioms that fail.
12. State the two step subspace test.
13. Let $W = \{(a, b, c) \in \mathbb{R}^3 : \text{where } a + b + c = 1\}$.
- (a) Use the two step subspace test to show $(W, +, \cdot)$ is a subspace.
 - (b) What geometric shape is W ? Hint I gave it in standard form.
 - (c) Give me the parametric equation for the geometric object defined in the set W .
14. Let $W = \{(x, y, z) \in \mathbb{R}^3 : \text{where } x - 3y - z = 0\}$.
- (a) Use the two step subspace test to show $(W, +, \cdot)$ is a subspace.
 - (b) What geometric shape is W ? Hint I gave it in standard form.
 - (c) Give me the parametric equation for the geometric object defined in the set W .

3 Linear Independence

15. Let $S = \{(1, 2, 1), (0, 1, 2), (0, -1, 0)\}$.
- (a) Is S linearly independent? (There is an easy test for this problem).
 - (b) Is $(2, 2, 2) \in \text{Span}(S)$? If yes what is a linear combination of the vectors in S that equals $(2, 2, 2)$?
 - (c) Does S span $\mathbb{R}^3$?
16. Let $S = \{x, x + 2, x^3 - x - 1, x^3\}$ be a set in P_3 . Use $v_1 = (0, 1, 0, 0)$, $v_2 = (2, 1, 0, 0)$, $v_3 = (-1, -1, 0, 1)$, and $v_4 = (0, 0, 0, 1)$.
- (a) Is S linearly independent?
 - (b) Is $x^3 + x^2 + x + 1 \in \text{Span}(S)$? If yes what is a linear combination of the polynomials in S that equals $x^3 + x^2 + x + 1$?
 - (c) Is $4x^3 - 2x \in \text{Span}(S)$? If yes what is a linear combination of the polynomials in S that equals $4x^3 - 2x$?
 - (d) Does S span P_3 ?

4 Span, Basis

17. Let $B = \{(1, 2, 1), (0, 1, 2), (0, -1, 0)\}$.
- (a) Is B a basis for $\mathbb{R}^3$
 - (b) Write the vector $(1, 0, -1)$ relative to the basis B .
 - (c) Write the vector (a, b, c) relative to the basis B .
 - (d) Find the change of basis matrix from the standard basis to the basis B . (we called it $P_{\text{STANDARD} \rightarrow B}$ in class).
18. For the following system of linear equations.
- $$\begin{array}{rrrrr} 2x_1 & -2x_2 & +4x_3 & & -6x_5 & = 2 \\ & & x_3 & +6x_4 & & = 0 \end{array}$$
- (a) Find the solution set.
 - (b) Find a basis for the solution set.
 - (c) What is the dimension of that solution set?
19. For the following subspace of P_3

$$W = \{a + bx + cx^2 + dx^3 : a = -c \text{ and } b = c + d\}$$

- (a) Find a basis for W .
- (b) What is the dimension of that solution set?

5 Change of Basis Matrix

20. Let $B = \{(1, 0), (0, 1)\}$, $B_1 = \{(-1, 1), (2, 3)\}$, and $B_2 = \{(1, -1), (1, 1)\}$.
- (a) Find the change of basis matrices for $P_{B_1 \rightarrow B_2}$ and $P_{B_1 \rightarrow B}$.
 - (b) Find the coordinates of the point $(4, 6)$ (given in the standard basis) relative to the bases B_1 and B_2 .
 - (c) Find the change of basis matrices for $P_{B \rightarrow B_2}$ and $P_{B_2 \rightarrow B}$.
 - (d) Find the coordinates of the point $(2, -4)$ (given in the standard basis) relative to the bases B and B_2 . Graph this point the two separate coordinate axes B and B_2 .

6 Row Space, Column Space & Null space

21. Let W be the plane $x - 2y + z = 0$ in $\mathbb{R}^3$.
- (a) Find the parametric equation for the plane.
 - (b) Find a basis for W .
 - (c) Compute the solution set to the linear system $x - 2y + z = 0$ in $\mathbb{R}^3$.
22. Let W be the hyperplane $x_1 - 2x_2 + x_3 + 6x_4 = 0$ in $\mathbb{R}^4$.
- (a) Find the parametric equation for the hyperplane.
 - (b) Find a basis for W .
 - (c) Compute the solution set to the linear system $x_1 - 2x_2 + x_3 + 6x_4 = 0$ in $\mathbb{R}^4$.
23. Let $A = \begin{bmatrix} -1 & 2 & 0 & 3 & 0 \\ 2 & 1 & 1 & -1 & 1 \\ 1 & 3 & 1 & 2 & 1 \end{bmatrix}$.
- (a) Find a basis for the Column Space of A , $\text{COL}(A)$, and the row space of A , $\text{ROW}(A)$.
 - (b) Compute the dimension of $\text{COL}(A)$ and $\text{ROW}(A)$.
 - (c) Find a basis for the null space of A , $\text{NULL}(A)$.
 - (d) Compute the dimension of $\text{NULL}(A)$.
24. The linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is given by the formula
- $$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} x + y \\ y + z \\ x - z \end{bmatrix}.$$
- (a) Find the matrix, A , to represent the linear transformation T .
 - (b) Compute the basis for the Range of T , which is the Column Space of A .
 - (c) Find a basis for the null space of A , $\text{NULL}(A)$.
 - (d) Compute the dimension of $\text{COL}(A)$ and $\text{NULL}(A)$. The dimension of the range of T is called the rank of T and the dimension of the null space is called the nullity.
 - (e) What is the dimension of the domain of T and the codomain of T ? Again, compare Rank, Nullity and the dimension of the Domain. Do you see a relation?

7 Basic Transformations

25. Write the matrix for the following transformations described below.
- (a) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is rotated by 45° counter-clockwise.
 - (b) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is reflected about the x -axis.
 - (c) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the x -axis is contracted by half and the y -axis is dilated by 2.
 - (d) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is rotated by 30° counter-clockwise and then reflected about the x -axis.
 - (e) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is reflected about the x -axis and then rotated by 30° counter-clockwise.
 - (f) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ where the x -axis is contracted by half and the z -axis is dilated by 2.

8 Eigenvalues, Eigenvectors and Diagonalization

26. ~~For the following matrices find the characteristic equation, the eigenvalues and their corresponding eigen-vectors.~~

$$A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \end{bmatrix}, B = \begin{bmatrix} 4 & 1 \\ -1 & 2 \end{bmatrix}, C = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, D = \begin{bmatrix} 6 & 3 & -8 \\ 0 & -2 & 0 \\ 1 & 0 & -3 \end{bmatrix}$$

and

$$E = \begin{bmatrix} 4 & 0 & -1 \\ 0 & 3 & 0 \\ 1 & 0 & 2 \end{bmatrix},$$

27. ~~for the above matrices, determine if they are diagonalizable. State why or why not. And if it is diagonalizable, diagonalize it. That is, find P and D .~~
28. ~~Diagonalize the matrix below.~~

$$\begin{bmatrix} 4 & 0 & -1 & -1 \\ 0 & 3 & 0 & -1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$