Math 3160 - Test 2 Review

Be certain to **know** the quizzes and . . .

1 Vectors

1. Find a unit vector that when postioned at the origin forms a 30° angle with the x-axis.

2. Find a vector of length three units that when postioned at the origin forms a 240° angle with the x-axis.

3. Let $\mathbf{v} = (1, 3, 4)$ and $\mathbf{w} = (1, -1, 0)$ be vectors in $\mathbb{R}^3$. and let $P(1, 1, 1)$ and $Q(0, -4, 0)$ be two points in $\mathbb{R}^3$.

   (a) Find a vector that is parallel to $\mathbf{v}$ and unit.

   (b) Compute $\|2\mathbf{v} - \mathbf{w}\|$.

   (c) Compute the angle between $\mathbf{v}$ and $\mathbf{w}$.

   (d) Find the equation of a plane containing P and with normal vector $\mathbf{v}$.

4. Find parametric equations for the line (in $\mathbb{R}^3$) so that

   (a) the line contains the point $P(0, 1, 2)$ and $Q(1, 2, 3)$.

   (b) the line contains the point $P(-5, 1, 3)$ and is parallel to the vector $(1, 2, 3)$.

5. Find equation (both the normal equation and the parametric equation) for the plane (in $\mathbb{R}^3$) so that

   (a) the plane contains the points $P(2, 2, 2)$, $Q(1, 2, 3)$ and $R(1, -1, 0)$.

   (b) the plane contains the origin and is perpendicular to the vector $(1, 2, 3)$.

   (c) the plane contains the point $(1, 2, 3)$ and contains the vectors $\mathbf{v} = (1, 0, -3)$ and $\mathbf{w} = (2, 1, 3)$.

6. Define the planes P_1 and P_2 as follows:

$$P_1 : x - 2y + z = 12$$

$$P_2 : 3x - 3y + z = 4$$

(a) What are the two normal vectors for the above planes.

(b) Find the angle between the two above planes.

(c) Find two pointsone on each of the above planes.

(d) Find set of all points that lay in both planes.

(e) The two planes intersect in a line, find the parametric equation of that line.

7. Define the planes P_1 and P_2 as follows:

$$P_1 : x - 2y + z = 12$$

$$P_2 : 3x - 6y + 3z = 4$$

Show the planes are parallel. Do they intersect? Find the solution set to their intersection.

8. Let $P(1, 0, 2, 0)$, $Q(0, 0, 2, -1)$, $R(0, 1, 1, 0)$ and $S(1, 1, 1, 0)$ be points in $\mathbb{R}^4$. Find the equation of the hyperplane (both the normal equation and the) that contains these four points.

9. For the hyperplane (in $\mathbb{R}^5$) given below: find its normal vector and find its parametric equation.

$$x_1 + -4x_3 + 2x_4 + x_5 = 3$$

10. Alice, Bob and Charlie rated a few of their favorite movies (listed below). Bob recommends to go see the new Dwayne "the Rock" Johnson movie but Charlie said not see it. From their movie ratings below find the angle between Bob and Alice and the angle between Charlie and Alice. What should Alice do?

	Baywatch	Furious 8	Moana	San Andreas	Jem	Furious 7	Scorpion King
Alice	4	5	9	4	7	5	10
Bob	2	6	2	5	4	3	10
Charlie	1	6	9	6	6	4	10

2 Vector Spaces and Subspaces

11. Let $V = \mathbb{R}^3$ equipped with usual vector addition and scalar multiplication. Prove V is a vector space. That is, prove all 10 Axioms.

12. Let $V = \mathbb{R}^2$. And define the two operations

$\oplus$: $(x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2 + 1, y_1 + y_2 + 1)$

$\odot$: $k \odot (x_1, y_1) = (kx_1, ky_1)$

(a) Compute $(0, 4) \oplus (-2, 3)$ and compute $2 \odot (1, 1)$.

(b) Show $\mathbf{0} \neq (0, 0)$.

(c) Show $\mathbf{0} = (-1, -1)$.

(d) Prove Axiom 5. That is, for each $\mathbf{v}$ find $-\mathbf{v}$ so that

$$\mathbf{v} \oplus -\mathbf{v} = \mathbf{0}.$$

(e) V does satisfy some of the vector space axioms, but not all of the axioms. Find two axioms that fail.

13. State the two step subspace test.

14. Let $W = \{(a, b, c) \in \mathbb{R}^3 : \text{ where } a + b + c = 1\}$.

    (a) Use the two step subspace test to show $(W, +, \cdot)$ is a subspace.

    (b) What geometric shape is W? Hint I gave it in standard form.

    (c) Give me the parametric for the geometric object defined in the set W.

15. Let $W = \{(x, y, z) \in \mathbb{R}^3 : \text{ where } x - 3y - z = 0\}$.

    (a) Use the two step subspace test to show $(W, +, \cdot)$ is a subspace.

    (b) What geometric shape is W? Hint I gave it in standard form.

    (c) Give me the parametric for the geometric object defined in the set W.

3 Linear Independence

16. Let $S = \{(1, 2, 1), (0, 1, 2), (0, -1, 0)\}$.

    (a) Is S linearlly independent? (There is an easy test for this problem).

    (b) Is $(2, 2, 2) \in \text{Span}(S)$? If yes what is a linear combination of the vectors in S that equals $(2, 2, 2)$?

    (c) Does S span $\mathbb{R}^3$?

17. Let $S = \{x, x+2, x^3 - x - 1, x^3\}$ be a set in P_3.

   (a) Is S linearlly independent?

   (b) Is $x^3 + x^2 + x + 1 \in \text{Span}(S)$? If yes what is a linear combination of the polynomials in S that equals $x^3 + x^2 + x + 1$?

   (c) Is $4x^3 - 2x \in \text{Span}(S)$? If yes what is a linear combination of the polynomials in S that equals $4x^3 - 2x$?

   (d) Does S span P_3?

4 Span, Basis

18. Let $B = \{(1,2,1), (0,1,2), (0,-1,0)\}$.

   (a) Is B a basis for $\mathbb{R}^3$

   (b) Write the vector $(1,0,-1)$ relative to the basis B.

   (c) Write the vector (a,b,c) relative to the basis B.

   (d) Find the change of basis matrix from the standard basis to the basis B. (we called it $P_{\text{STANDARD}\to B}$ in class).

19. For the following system of linear equations.

$$\begin{array}{ccccccc} 2x_1 & -2x_2 & +4x_3 & & -6x_5 & = 2 \\ & & x_3 & +6x_4 & & = 0 \end{array}$$

   (a) Find the solution set.

   (b) Find a basis for the solution set.

   (c) What is the dimension of that solution set?

20. For the following subspace of P_3

$$W = \{a + bx + cx^2 + dx^3 : a = -c \text{ and } b = c + d\}$$

   (a) Find a basis for W.

   (b) What is the dimension of that solution set?

5 Change of Basis Matrix

21. Let $B = \{(1,0), (0,1)\}$, $B_1 = \{(-1,1), (2,3)\}$ and $B_2 = \{(1,-1), (1,1)\}$.

(a) Find the change of basis matrices for $P_{B_1 \to B_2}$ and $P_{B_1 \to B_2}$.

(b) Find the coordinates of the point $(4, 6)$ (given in the standard basis) relative to the bases B_1 and B_2.

(c) Find the change of basis matrices for $P_{B \to B_2}$ and $P_{B_2 \to B}$.

(d) Find the coordinates of the point $(2, -4)$ (given in the standard basis) relative to the bases B and B_2. Graph this point the two separate coordinate axes B and B_2.

6 Row Space, Column Space & Null space

22. Let W be the plane $x - 2y + z = 0$ in $\mathbb{R}^3$.

(a) Find the parametric equation for the plane.

(b) Find a basis for W.

(c) Compute the solution set to the linear system $x - 2y + z = 0$ in $\mathbb{R}^3$.

23. Let W be the hyperplane $x_1 - 2x_2 + x_3 + 6x_4 = 0$ in $\mathbb{R}^4$.

(a) Find the parametric equation for the hyperplane.

(b) Find a basis for W.

(c) Compute the solution set to the linear system $x_1 - 2x_2 + x_3 + 6x_4 = 0$ in $\mathbb{R}^4$.

24. Let $A = \begin{bmatrix} -1 & 2 & 0 & 3 & 0 \\ 2 & 1 & 1 & -1 & 1 \\ 1 & 3 & 1 & 2 & 1 \end{bmatrix}$.

(a) Find a basis for the Column Space of A, COL(A), and the row space of A, ROW(A).

(b) Compute the dimension of COL(A) and ROW(A).

(c) Find a basis for thenull space of A, NULL(A).

(d) Compute the dimension of NULL(A).

25. The linear transformation $T : \mathbb{R}^3 \to \mathbb{R}^3$ is given by the formula $T(\begin{bmatrix} x \\ y \\ z \end{bmatrix}) = \begin{bmatrix} x+y \\ y+z \\ x-z \end{bmatrix}$.

(a) Find the matrix, A, to represent the linear trasformation T.

(b) Compute the basis for the Range of T, which is the Column Space of A.

(c) Find a basis for the null space of A, NULL(A).

(d) Compute the dimension of COL(A) and NULL(A). The dimension of the range of T is called the rank of T and the dimension of the null space is called the nullity.

(e) What is the dimension of the domain of T and the codomain of T? Again, compare Rank, Nullity and the dimension of the Domain. Do you see a relation?

7 Basic Transformations

26. Write the matrix for the following transformations described below.

(a) $T : \mathbb{R}^2 \to \mathbb{R}^2$ where the plane is rotated by 45° counter-clockwise.

(b) $T : \mathbb{R}^2 \to \mathbb{R}^2$ where the plane is reflected about the x-axis.

(c) $T : \mathbb{R}^2 \to \mathbb{R}^2$ where the x-axis is contracted by half and the y-axis is dilated by 2.

(d) $T : \mathbb{R}^2 \to \mathbb{R}^2$ where the plane is rotated by 30° counter-clockwise and then reflected about the x-axis.

(e) $T : \mathbb{R}^2 \to \mathbb{R}^2$ where the plane is reflected about the x-axis and then rotated by 30° counter-clockwise.

(f) $T : \mathbb{R}^3 \to \mathbb{R}^3$ where the x-axis is contracted by half and the z-axis is dilated by 2.

8 Eigenvalues, Eigenvectors and Diagonalization

27. For the following matrices find the charactersitic equation, the eigenvalues and their cooresponding eigen vectors.

$$A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \end{bmatrix}, B = \begin{bmatrix} 4 & 1 \\ -1 & 2 \end{bmatrix}, C = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, D = \begin{bmatrix} 6 & 3 & -8 \\ 0 & -2 & 0 \\ 1 & 0 & -3 \end{bmatrix}$$

and

$$E = \begin{bmatrix} 4 & 0 & -1 \\ 0 & 3 & 0 \\ 1 & 0 & 2 \end{bmatrix},$$

28. for the above matrices, determine if they are diagonalizable. State why or why not. And if it is diagonalizable, diagonaalize it. That is, find P and D.

29. Diagonalize the matrix below.
$$\begin{bmatrix} 4 & 0 & -1 & -1 \\ 0 & 3 & 0 & -1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$