

Math 3160 - Test 2

Name: _____

1. Let $V = \mathbb{R}^2$. And define the two operations

$$\oplus: (x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2 + 1, y_1 + y_2 - 1)$$

$$\odot: k \odot (x_1, y_1) = (kx_1, y_1)$$

- (a) Prove (or disprove) the V is closed under vector addition (Axiom 1).
(b) Note V has a zero vector. What is the zero vector for V

2. Let $W = \{(a, b, c) \in \mathbb{R}^3 : \text{ where } a = 0\}$. Use the two step subspace test to show $(W, +, \cdot)$ is a subspace.

3. Let $S = \{x + 1, 2x^2 - 3x - 3, x^2\}$ be a set in P_2 .
- (a) Is S linearly independent?
 - (b) Is $-2x \in \text{Span}(S)$? If yes what is a linear combination of the polynomials in S that equals $-2x$?
 - (c) Does S span P_2 ?

4. Let $B = \{(1, 0, 1), (0, 1, 2), (1, -1, 0)\}$.
- (a) Is B a basis for $\mathbb{R}^3$
 - (b) Write the vector $(1, 0, -1)$ relative to the basis B .

5. Let $B_1 = \{(1, 2), (-3, 1)\}$, $B_2 = \{(-1, 1), (2, 3)\}$.
- (a) Find the change of basis matrices for $P_{B_1 \rightarrow B_2}$ and $P_{B_2 \rightarrow B_1}$.
 - (b) Find the coordinates of the point $(4, 6)$ (given in the standard basis) relative to the bases B_1 and B_2 . Here you may need $P_{\text{STANDARD} \rightarrow B_1}$.

6. The linear transformation $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$ is given by the formula

$$T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}\right) = \begin{bmatrix} x_1 - x_3 \\ x_2 \\ x_4 \end{bmatrix}.$$

- (a) Find the matrix, A , to represent the linear transformation T .
- (b) Compute the basis for the Range of T .
- (c) Find a basis for the null space of A , $\text{NULL}(A)$.
- (d) Find the rank and nullity.
- (e) What is the dimension of the domain of T and the codomain of T ? Compare Rank, Nullity and the dimension of the Domain.

7. Write the matrix for the following transformations described below.
- (a) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is rotated by 60° counter-clockwise.
 - (b) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where the plane is reflected about the y -axis and then rotated by 60° counter-clockwise.
 - (c) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ where the y -axis is contracted by a factor of $1/3$ and the z -axis is dilated by 3 .

8. Diagonalize the matrix below.

$$\begin{bmatrix} 3 & 0 & -1 \\ 0 & 1 & 3 \\ 0 & 1 & -1 \end{bmatrix}$$